

Neuvièmes journées de Statistique Mathématique : Learning (and) statistics with Talagrand.

**A story of $\nu_n(h)$ through nonparametric inference for
regression and diffusions.**

Fabienne Comte *MAP5, CNRS 8145, Université Paris Cité*

Plan of the talk

A twenty-years small story.

- 1 Regression and diffusion models and their least-squares contrasts
- 2 Norm equivalence: from Bernstein Inequality to Tropp Chernov deviation (2012)
- 3 Risk bound for adaptive estimator and the Talagrand (1996) deviation Inequality.

Projection estimators and model selection

Choose a basis φ_j such that $\langle \varphi_j, \varphi_k \rangle = \int_A \varphi_j(x) \varphi_k(x) dx = \delta_{j,k}$ and set

$$S_m = \text{Vect}(\varphi_1, \dots, \varphi_m), \quad \text{Support}(\varphi_j) = A \subset \mathbb{R}$$

Let b denote the function we want to estimate on A ($b_A = b \mathbf{1}_A$).

- Define

$$\hat{b}_m = \sum_{j=1}^m \hat{a}_j \varphi_j, \quad \hat{a}_j \text{ computed from the observations.}$$

and prove a bound on $\mathbb{E} \left(\|\hat{b}_m - b_A\|_n^2 \right) := \mathbb{E}(m)$ and on $\mathbb{E} \left(\|\hat{b}_m - b_A\|_f^2 \right)$,

- Next, choose m from the observations:

$$\hat{m} = \arg \min_{m \in \mathcal{M}_n} \text{Crit}(m), \quad \mathcal{M}_n \subset \mathbb{N}.$$

and prove a bound on $\mathbb{E} \left(\|\hat{b}_{\hat{m}} - b_A\|_n^2 \right)$ of order

$$C \inf_{m \in \mathcal{M}_n} \mathbb{E}(m) + \text{negligible terms.}$$

A cascade of models

- 1 Usual (homoscedatic) regression model

$$\mathbf{Y}_i = \mathbf{b}(\mathbf{X}_i) + \sigma \varepsilon_i, \quad i = 1, \dots, n, \quad \text{with } X_i \text{ i.i.d.}, \varepsilon_i \text{ i.i.d. } (0, 1),$$

and $(X_i)_i \perp (\varepsilon_i)_i$. **Observations** $(X_i, Y_i)_{1 \leq i \leq n}$.

- 2 Autoregressive model.

$$\mathbf{X}_{i+1} = \mathbf{b}(\mathbf{X}_i) + \varepsilon_i, \quad i = 1, \dots, n, \quad \text{with } \varepsilon_i \text{ i.i.d. } (0, 1).$$

The X_i 's are not independent and neither the sequences $(X_i)_i$ and (ε_i) .

Observations $(X_i)_{1 \leq i \leq n+1}$.

- 3 Diffusion model

$$d\mathbf{X}_t = \mathbf{b}(\mathbf{X}_t)dt + \sigma(\mathbf{X}_t)d\mathbf{W}_t \quad \text{with } X_0 \sim \mu$$

and W_t a standard Brownian motion. **Observations** $(X_{i\Delta})_{1 \leq i \leq n}$.

Δ small and $n\Delta$ large (high frequency data)

- 4 Diffusion models in FDA spirit.

$$d\mathbf{X}_t^{(i)} = \mathbf{b}(\mathbf{X}_t^{(i)})dt + \sigma(\mathbf{X}_t^{(i)})d\mathbf{W}_t^{(i)}, \quad X_0^{(i)} = x_0,$$

$W^{(i)}$ independent standard brownian motions, T fixed. **Observations**
 n independent paths ; $(X_t^{(i)})_{t \in [0, T]}, i = 1, \dots, n$.

Link with regression (1)

Model 1 = standard regression, i.i.d. variables, unbounded noise.

Model 2 = autoregression,

- variables X_i can be identically distributed
- no independence between the X_i 's \Rightarrow mixing to handle dependency,
- Sequences $(\varepsilon_i)_i$ and $(X_i)_i$ no longer independent \Rightarrow conditioning by $X = x$ no longer possible,
- martingale properties
- unbounded noise.

Link with regression (2)

Model 3. We define

$$Y_{i,\Delta} = \frac{X_{(i+1)\Delta} - X_{i\Delta}}{\Delta},$$

and we have

❶ Approximation 1

$$Y_{i,\Delta} = b(X_{i\Delta}) + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} \sigma(X_s) dW_s}_{:=Z_{i,\Delta}} + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} [b(X_s) - b(X_{i\Delta})] ds}_{R_{i,\Delta}^{(1)}}.$$

❷ Approximation 2

$$\begin{aligned} Y_{i,\Delta} &= b(X_{i\Delta}) + \underbrace{\sigma(X_{i\Delta}) \frac{W_{(i+1)\Delta} - W_{i\Delta}}{\Delta}}_{x,w \text{ separated}} + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} [b(X_s) - b(X_{i\Delta})] ds}_{R_{i,\Delta}^{(1)}} \\ &+ \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} [\sigma(X_s) - \sigma(X_{i\Delta})] dW_s}_{:=R_{i,\Delta}^{(2)}}. \end{aligned}$$

Link with regression (3)

Model 3.

- Approximation 1 with martingale tools only,
- Approximation 2 with Talagrand-type deviation.

Model 4. Back to independence: n independent complete paths are available.

Definition of the estimator

$$\hat{b}_m = \arg \min_{h \in S_m} \gamma_n(h)$$

with

$$\textcircled{1} \text{ Model 1. } \gamma_n(h) = \underbrace{\frac{1}{n} \sum_{i=1}^n h^2(X_i)}_{:= \|h\|_n^2} - \frac{2}{n} \sum_{i=1}^n Y_i h(X_i)$$

$$\textcircled{2} \text{ Model 2. } \gamma_n(h) = \underbrace{\frac{1}{n} \sum_{i=1}^n h^2(X_i)}_{:= \|h\|_n^2} - \frac{2}{n} \sum_{i=1}^n X_{i+1} h(X_i)$$

$$\textcircled{3} \text{ Model 3. } \gamma_n(h) = \underbrace{\frac{1}{n} \sum_{i=1}^n h^2(X_{i\Delta})}_{:= \|h\|_n^2} - \frac{2}{n} \sum_{i=1}^n Y_{i,\Delta} h(X_{i\Delta})$$

$$\textcircled{4} \text{ Model 4. } \gamma_n(h) = \underbrace{\frac{1}{nT} \sum_{i=1}^n \int_0^T h^2(X_s^{(i)}) ds}_{:= \|h\|_n^2} - \frac{2}{n} \sum_{i=1}^n \int_0^T h(X_s^{(i)}) dX_s^{(i)}.$$

Definition of the estimator

$$\text{Let } \hat{\Psi}_m = (\langle \varphi_j, \varphi_k \rangle_n)_{1 \leq j, k \leq m} = \frac{1}{n} \hat{\Phi}_m^T \hat{\Phi}_m, \quad \hat{\Phi}_m := (\varphi_j(X_i))_{1 \leq i \leq n, 1 \leq j \leq m}$$

$$\langle \varphi_j, \varphi_k \rangle_n = \frac{1}{n} \sum_{i=1}^n \varphi_j(X_i) \varphi_k(X_i).$$

Assume that $\hat{\Psi}_m$ is invertible, then

$$\hat{b}_m = \sum_{j=1}^m \hat{a}_j \varphi_j, \quad \hat{\mathbf{a}}_m := \begin{pmatrix} \hat{a}_1 \\ \vdots \\ \hat{a}_m \end{pmatrix} = \hat{\Psi}_m^{-1} \mathbf{Z}_m$$

and

$$\mathbf{Z}_m = \begin{cases} \frac{1}{n} \hat{\Phi}_m^T \mathbf{Y}, & \mathbf{Y} = (Y_1, \dots, Y_n)^T \\ \frac{1}{nT} \sum_{i=1}^n \int_0^T \varphi_j(X_s^{(i)}) dX_s^{(i)} \end{cases}$$

Risk bound in empirical norm on a fixed model

Sometimes almost "free", with projection arguments.

Model 1. Let $(X_i, Y_i)_{1 \leq i \leq n}$ be observations drawn from model (1) and set $b_A = b \mathbf{1}_A$. Assume that $b_A \in \mathbb{L}^2(A, f(x)dx)$ and that $\hat{\Psi}_m$ is a.s. invertible. Consider the least squares estimator \hat{b}_m of b , defined as the contrast minimizer. Then

$$\begin{aligned} \mathbb{E}[\|\hat{b}_m - b_A\|_n^2] &= \mathbb{E} \left(\inf_{h \in S_m} \|h - b_A\|_n^2 \right) + \sigma_\varepsilon^2 \frac{m}{n}, \\ &\leq \underbrace{\inf_{h \in S_m} \left[\int (b_A - h)^2(x) f(x) dx \right]}_{\|b_A - h\|_f^2} + \sigma_\varepsilon^2 \frac{m}{n}. \end{aligned}$$

Questions arise to handle $\mathbb{E}[\|\hat{b}_m - b_A\|_f^2]$ and for $\mathbb{E}[\|\hat{b}_{\hat{m}} - b_A\|_n^2]$.

Tropp Chernov Deviation inequality

Risk bound in integrated norm on a fixed model

Recall that f denotes the density of X_1 and write for $b_m \in S_m$,

$$\mathbb{E}[\|\hat{b}_m - b_A\|_f^2] \leq 2(\|b_m - b_A\|_f^2 + \mathbb{E}[\|\hat{b}_m - b_m\|_f^2]).$$

To handle $\mathbb{E}[\|\hat{b}_m - b_m\|_f^2]$, we need a comparison of

$$\|h\|_n^2 \quad \text{and} \quad \int h^2(x)f(x)dx = \|h\|_f^2, \quad \boxed{\text{for } t \in S_m},$$

or equivalently of

$$\hat{\Psi}_m = (\langle \varphi_j, \varphi_k \rangle_n)_{1 \leq j, k \leq m} \quad \text{to} \quad \Psi_m = \mathbb{E}(\hat{\Psi}_m) = (\langle \varphi_j, \varphi_k \rangle_f)_{1 \leq j, k \leq m}.$$

First idea:

$$\|h\|_n^2 - \|h\|_f^2 = \frac{1}{n} \sum_{i=1}^n [h^2(X_i) - \mathbb{E}(h^2(X_i))].$$

Looks like a centered empirical process.

Key set to control

First strategies: **Bernstein inequalities** for

$$\nu_n(h^2) = \frac{1}{n} \sum_{i=1}^n [h^2(X_i) - \mathbb{E}(h^2(X_i))] = \|h\|_n^2 - \|h\|_f^2.$$

Quadratic! \Rightarrow **ugly** computations and union bounds.

Define the set where the empirical and the $\mathbb{L}^2(A, f)$ norms are equivalent for functions in S_m :

$$\Omega_m(\delta) = \left\{ \sup_{h \in S_m, h \neq 0} \left| \frac{\|h\|_n^2}{\|h\|_f^2} - 1 \right| \leq \delta \right\}, \quad \text{for } \delta \in (0, 1). \quad (1)$$

It holds that for Ψ_m invertible,

$$\Omega_m(\delta) = \left\{ \|\Psi_m^{-1/2} \hat{\Psi}_m \Psi_m^{-1/2} - \text{Id}_m\|_{\text{op}} \leq \delta \right\}.$$

On $\Omega_m(\frac{1}{2})$, for a vector $x \in \mathbb{R}^m$,

$$x^t \hat{\Psi}_m x \leq (3/2)x^t \Psi_m x \text{ and } x^t \hat{\Psi}_m^{-1} x \leq 2x^t \Psi_m^{-1} x.$$

Theorem (Matrix Chernoff, Tropp (2012))

Theorem

Consider a finite sequence $\{\mathbf{U}_i\}$ of independent, random, self-adjoint matrices with dimension d . Assume that each random matrix satisfies

$$\mathbf{U}_i \geq 0 \quad \text{and} \quad \lambda_{\max}(\mathbf{U}_i) \leq R \quad \text{almost surely.}$$

Define $\mu_{\min} := \lambda_{\min}(\sum_k \mathbb{E}(\mathbf{U}_i))$ and $\mu_{\max} := \lambda_{\max}(\sum_k \mathbb{E}(\mathbf{U}_i))$. Then

$$\mathbb{P} \left\{ \lambda_{\min} \left(\sum_i \mathbf{U}_i \right) \leq (1 - \delta) \mu_{\min} \right\} \leq d \left[\frac{e^{-\delta}}{(1 - \delta)^{1-\delta}} \right]^{\mu_{\min}/R} \quad \text{for } \delta \in [0, 1],$$

$$\mathbb{P} \left\{ \lambda_{\max} \left(\sum_i \mathbf{U}_i \right) \geq (1 + \delta) \mu_{\max} \right\} \leq d \left[\frac{e^{\delta}}{(1 + \delta)^{1+\delta}} \right]^{\mu_{\max}/R} \quad \text{for } \delta \geq 0.$$

Apply Tropp-Chernov

$$\Psi_m^{-1/2} \hat{\Psi}_m \Psi_m^{-1/2} = \frac{1}{n} \sum_{i=1}^n \Psi_m^{-1/2} \Xi_i \Psi_m^{-1/2}, \quad \Xi_i = (\varphi_j(X_i) \varphi_k(X_i))_{1 \leq j, k \leq m}.$$

$$\mathbf{U}_i = \frac{1}{n} \Psi_m^{-1/2} \Xi_i \Psi_m^{-1/2}, \quad \mathbb{E}(\mathbf{U}_i) = \frac{1}{n} \mathbf{Id}_m.$$

$$\Rightarrow \mu_{\min} = \mu_{\max} = 1$$

and

$$R = \frac{1}{n} L(m) \|\Psi_m^{-1}\|_{\text{op}}$$

where

$$\sup_{x \in A} \sum_{j=1}^m \varphi_j^2(x) \leq L(m) (< +\infty).$$

Applied first by Cohen *et al.* (2013), Tropp-Chernov inequality provides the adequate inequality.

Proposition

Let $\hat{\Psi}_m, \Psi_m$ be the $m \times m$ matrices defined in above and assume that Ψ_m is invertible. Then for all $0 < \delta \leq 1$,

$$\begin{aligned} \mathbb{P}(\Omega_m(\delta)^c) &= \mathbb{P}\left[\|\Psi_m^{-1/2}\hat{\Psi}_m\Psi_m^{-1/2} - \text{Id}_m\|_{\text{op}} > \delta\right] \\ &\leq 2m \exp\left(-c(\delta)\frac{n}{L(m)(\|\Psi_m^{-1}\|_{\text{op}} \vee 1)}\right), \end{aligned}$$

where $c(\delta) = (1 + \delta) \log(1 + \delta) - \delta$.

Stability condition

Fix $\delta = 1/2$. As a consequence, if m is such that **(stability condition)**:

$$L(m) (\|\Psi_m^{-1}\|_{\text{op}} \vee 1) \leq \frac{\mathfrak{c}(p)}{2} \frac{n}{\log(n)}, \quad (2)$$

with

$$\mathfrak{c}(p) = \frac{3 \log(3/2) - 1}{p + 1},$$

we obtain

$$\mathbb{P} \left[\left(\Omega_m \left(\frac{1}{2} \right) \right)^c \right] \leq \frac{2}{n^p}.$$

Condition (2) refers to a deterministic matrix, suggests a cutoff

$$\tilde{b}_m = \hat{b}_m \mathbf{1}_{\hat{\Lambda}_m}, \quad \hat{\Lambda}_m = \left\{ L(m) (\|\hat{\Psi}_m^{-1}\|_{\text{op}} \vee 1) \leq \frac{\mathfrak{c}(p)}{2} \frac{n}{\log(n)} \right\}.$$

Proposition

Assume that $\mathbb{E}(\varepsilon_1^4) < +\infty$ and $b_A \in \mathbb{L}^4(A, f(x)dx)$. Then for any m satisfying (2), we have

$$\mathbb{E}[\|\tilde{b}_m - b_A\|_f^2] \leq \left(1 + \frac{8c}{\log(n)}\right) \inf_{t \in S_m} \|b_A - t\|_f^2 + 8\sigma_\varepsilon^2 \frac{m}{n} + \frac{c}{n}, \quad (3)$$

where c is a constant depending on $\mathbb{E}(\varepsilon_1^4)$ and $\int b_A^4(x) f(x) dx$.

"Compact support" case

Case A compact and f lower bounded on A ,

$$\forall x \in A, \quad f(x) \geq f_0.$$

Then

$$\|\Psi_m^{-1}\|_{\text{op}} \leq \frac{1}{f_0}.$$

Condition (2) (stability) is fulfilled if

$$L(m) \leq f_0 \frac{c(p)}{2} \frac{n}{\log(n)}.$$

Better than first constraints given with $L(m) = m$, Baraud (2002), Baraud et al (2001).

$\|\hat{\Psi}_m^{-1}\|_{\text{op}}$ is an empirical version that avoids to estimate f_0 !

What about models 2, 3, 4?

The matrix $\hat{\Psi}_m$ only depends on the X_i or $X_{i\Delta}$ or $(X_t^{(i)})_{t \in [0, T]}$.

⇒ Possible to extend to dependent data, with coupling methods.

The story:

- First attempts in Baraud (2000), (2002) around the Gram matrix, Bernstein deviation, deterministic collection and compactly supported bases,
- Dependent case, Baraud *et al* (2000, 2001), SDEs Comte *et al.* (2007),
- Stability condition Cohen *et al.* (2013), (2019)
- Random collections for possibly non compact cases, Comte and Genon-Catalot (2020), and Tropp for dependent variables (2021). Recently improved by Yichuan Huang.

For the future:

- Tropp applied for **regular** collections of models, what if $L(m) = n$ and the cardinal of the collection is exponential?
- The non bounded case.
Questions arise in FDA

$$\hat{\Psi}_m = \left(\frac{1}{n} \sum_{i=1}^n \langle \varphi_j, X_i \rangle \langle \varphi_k, X_i \rangle \right)_{1 \leq j, k \leq m}$$

No longer bounded (Computing R).

Talagrand deviation Inequality

Collection of models

Condition (2) also defines a collection of models, which will become random ($\Psi_m \rightarrow \hat{\Psi}_m$):

$$\mathcal{M}_n = \left\{ m \in \{1, \dots, n\}, L(m) (\|\Psi_m^{-1}\|_{\text{op}} \vee 1) \leq \frac{c(p)}{2} \frac{n}{\log(n)} \right\}$$

$$\mathcal{M}_n^+ = \left\{ m \in \{1, \dots, n\}, L(m) (\|\Psi_m^{-1}\|_{\text{op}} \vee 1) \leq 2c(p) \frac{n}{\log(n)} \right\}$$

$$\hat{\mathcal{M}}_n = \left\{ m \in \{1, \dots, n\}, L(m) (\|\hat{\Psi}_m^{-1}\|_{\text{op}} \vee 1) \leq c(p) \frac{n}{\log(n)} \right\}$$

$$\hat{m} = \arg \min_{m \in \hat{\mathcal{M}}_n} \left(\gamma_n(\hat{b}_m) + \text{pen}(m) \right).$$

Decomposition of the contrast

$$\gamma_n(h) = \|h\|_n^2 - \frac{2}{n} \sum_{i=1}^n \underbrace{Y_i h(X_i)}_{\text{Model1}} / \underbrace{X_{i+1} h(X_i)}_{\text{Model2}} / \underbrace{Y_{i\Delta} h(X_{i\Delta})}_{\text{Model3}}$$

leading to

$$\gamma_n(h) - \gamma_n(\ell) = \|h - b\|_n^2 - \|\ell - b\|_n^2 - 2\nu_n(h - \ell) + \text{residual},$$

$$\nu_n(h) = \frac{1}{n} \sum_{i=1}^n \varepsilon_i h(X_i) \quad \Rightarrow h \mapsto \nu_n(h) \text{ is now linear.}$$

Then

$$\hat{m} = \arg \min_{m \in \hat{\mathcal{M}}_n} \left(\gamma_n(\hat{b}_m) + \text{pen}(m) \right)$$

implies that for all $m \in \hat{\mathcal{M}}_n$

$$\gamma_n(\hat{b}_{\hat{m}}) + \text{pen}(\hat{m}) \leq \gamma_n(\hat{b}_m) + \text{pen}(m)$$

For all $m \in \widehat{\mathcal{M}}_n$

$$\|\widehat{b}_{\widehat{m}} - b\|_n^2 \leq \|\widehat{b}_m - b\|_n^2 + \text{pen}(m) + 2\nu_n(\widehat{b}_{\widehat{m}} - \widehat{b}_m) - \text{pen}(\widehat{m}).$$

Let $\Omega_n = \bigcap_m \Omega_m$. Then

$$\Xi_n = \left\{ \mathcal{M}_n \subset \widehat{\mathcal{M}}_n \subset \mathcal{M}_n^+ \right\} \text{ satisfies } \Omega_n \subset \Xi_n.$$

So, on Ω_n , for all $m \in \mathcal{M}_n$,

$$\|\widehat{b}_{\widehat{m}} - b\|_n^2 \leq \|\widehat{b}_m - b\|_n^2 + \text{pen}(m) + 2\nu_n(\widehat{b}_{\widehat{m}} - \widehat{b}_m) - \text{pen}(\widehat{m}),$$

and $\widehat{m} \in \mathcal{M}_n^+$. Then prove

$$\mathbb{E} \left[\left(\sup_{h \in S_{\widehat{m}}, \|h\|_f=1} \nu_n^2(h) - p(\widehat{m}) \right)_+ \mathbf{1}_{\Omega_n} \right] \lesssim \frac{C}{n}$$

with

$$\mathbb{E} \left[\left(\sup_{h \in S_{\widehat{m}}, \|h\|_f=1} \nu_n^2(h) - p(\widehat{m}) \right)_+ \mathbf{1}_{\Omega_n} \right] \leq \sum_{m \in \mathcal{M}_n^+} \mathbb{E} \left[\left(\sup_{h \in S_m, \|h\|_f=1} \nu_n^2(h) - p(\widehat{m}) \right)_+ \right].$$

Theorem (Talagrand, Klein and Rio)

Theorem

Consider \mathcal{F} a class at most countable of measurable functions, and $(X_i)_{i \in \{1, \dots, n\}}$ a indep random variables. For $f \in \mathcal{F}$, let

$$\nu_n(f) = \frac{1}{n} \sum_{i=1}^n (f(X_i) - \mathbb{E}[f(X_i)]).$$

Then for all $\epsilon > 0$,

$$\begin{aligned} & \mathbb{E} \left[\left(\sup_{f \in \mathcal{F}} |\nu_n(f)|^2 - 2(1 + 2\epsilon)H^2 \right)_+ \right] \\ & \leq \frac{4}{b} \left[\frac{v}{n} \exp \left(-b\epsilon \frac{nH^2}{v} \right) + \frac{49M_1^2}{bC^2(\epsilon)n^2} \exp \left(-\frac{\sqrt{2}bC(\epsilon)\sqrt{\epsilon} nH}{7M_1} \right) \right] \end{aligned}$$

$$\sup_{f \in \mathcal{F}} \|f\|_\infty \leq M_1, \quad \mathbb{E}[\sup_{f \in \mathcal{F}} |\nu_n(f)|] \leq H, \quad \text{and} \quad \sup_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n \text{Var}(f(X_i)) \leq v.$$

and $C(\epsilon) = (\sqrt{1 + \epsilon} - 1) \wedge 1$, and $b = \frac{1}{6}$.

What is needed for applying Talagrand Inequality?

- A **countable** set of functions.
By density arguments, $\mathcal{F} \rightarrow$ unit ball of a linear normed space, as $f \rightarrow \nu_n(f)$ is continuous and \mathcal{F} contains a countable dense family.
- $f(e, x) = eh(x)$ should be **bounded**, and this requires the noise ε to be bounded.
- The variables are **independent**.
They may be so, or not...
Variance inequalities for mixing sequences : Doukhan (1994), Doukhan, Massart, Rio (1995), Rio (2000).
Stationary dependency with β -mixing can be handled by coupling methods (Berbee (1979), Viennet (1997)).

Application in regression with bounded noise.

Model 1. Barron, Birgé and Massart (1999), bounded noise:

$$\forall i \in \{1, \dots, n\}, \quad |\varepsilon_i| \leq K.$$

and compact set, to obtain a result.

$$\mathbb{H}^2 = \sigma_\varepsilon^2 \frac{m}{n} \propto \text{pen}(m), \quad v = \sigma_\varepsilon^2, \quad M_1 = K\sqrt{m}/\sqrt{f_0}.$$

$$\mathbb{E} \left[\left(\sup_{h \in S_m, \|h\|_f=1} \nu_n^2(h) - 2(1 + 2\varepsilon)\mathbb{H}^2 \right)_+ \right] \leq \frac{C_1}{n} \left(e^{-C_2 m} + \frac{K^2 m}{f_0 n} e^{-C_3 \sqrt{f_0} \sqrt{n}/K} \right).$$

Sum over $m \in \mathcal{M}_n$ are of order $1/n$.

Baraud (2000) proposes an integration of the deviation inequality.

Naive way:

$$\nu_n(h) = \nu_{n,1}(h) + \nu_{n,2}(h), \quad \nu_{n,1}(h) = \frac{1}{n} \sum_{i=1}^n \varepsilon_{i,1} h(X_i)$$

with

$$\varepsilon_{i,1} = \varepsilon_i \mathbf{1}_{|\varepsilon_i| \leq K} - \mathbb{E}(\varepsilon_i \mathbf{1}_{|\varepsilon_i| \leq K}).$$

Take $K = K(n)$, and $K(n) = \mathbf{c}\sqrt{n}/\log(n)$, for collection of models with cardinality n , in the previous

$$\mathbb{E} \left[\left(\sup_{h \in S_m, \|h\|_f=1} \nu_{n,1}^2(h) - \underbrace{2(1+2\epsilon)\mathbb{H}^2}_{\sim \text{pen}(m)} \right)_+ \right] \leq \frac{C_1}{n} \left(e^{-C_2 m} + \frac{K^2 m}{f_0 n} e^{-C_3 \sqrt{f_0 n}/K} \right).$$

\Rightarrow keep an order $1/n$.

$$\mathbb{E} (|\varepsilon_1|^2 \mathbf{1}_{|\varepsilon_1| > K(n)}) \leq \frac{\mathbb{E} (|\varepsilon_1|^{2+q})}{K(n)^q} = \frac{\log^q(n)}{\mathbf{c}^q n^q} \mathbb{E} (|\varepsilon_1|^{2+q}).$$

Choose q , deduce the required moment condition on the noise.

Non compact case: replace f_0^{-1} by $\|\Psi_m^{-1}\|_{\text{op}}$ with stability constraint

$$L(m)(\|\Psi_m^{-1}\|_{\text{op}} \vee 1) \leq \frac{c(p)}{2} \frac{n}{\log(n)}$$

and get

$$\begin{aligned} & \mathbb{E} \left[\left(\sup_{h \in S_m, \|h\|_f=1} \nu_{n,1}^2(h) - 2(1+2\epsilon)\mathbb{H}^2 \right)_+ \right] \\ & \leq \frac{C_1}{n} \left(e^{-C_2 m} + \frac{K^2}{\log(n)} e^{-C_3 \sqrt{mL(m)} \sqrt{\log(n)/K^2}} \right). \end{aligned}$$

Need K of order $\sqrt{\log(n)}$ (or $\log(n)$) \Rightarrow **Subgaussian** types conditions on the ε_i 's.

Dependent variables.

For \mathcal{U} and \mathcal{V} two σ -fields,

$$\beta(\mathcal{U}, \mathcal{V}) = \frac{1}{2} \sup \left\{ \sum_i \sum_j |\mathbb{P}(U_i)\mathbb{P}(V_j) - \mathbb{P}(U_i \cap V_j)| \right\}$$

where the supremum is taken over all finite partitions $(U_i)_{i \in I}$ and $(V_j)_{j \in J}$ of Ω , which are respectively \mathcal{U} and \mathcal{V} measurable.

For Y a strictly stationary sequence,

$$\beta_k(Y) = \beta(\mathcal{F}_0, \mathcal{G}_k) \text{ with } \mathcal{F}_0 = \sigma(Y_i, i \leq 0) \text{ and } \mathcal{G}_k = \sigma(Y_i, i \geq k)$$

First example of handling dependent (β -mixing) variables for model selection: Viennet (1997) for density estimation, empirical process

$$\frac{1}{n} \sum_{i=1}^n [f(X_i) - \mathbb{E}(f(X_i))].$$

Penalization from a variance bound for \mathbb{H}^2 involves the mixing coefficients.

Dependent variables in autoregression.

Here $X_{i+1} = b(X_i) + \varepsilon_i$, the dependent variables are

$$u_i := (X_i, \varepsilon_i),$$

with $(X_i$ and $\varepsilon_i)$ independent for fixed i .

Under conditions on b and the initial value, the sequence X_i and then u_i is stationary and β -mixing, i.e. $\beta_k(u), \beta_k(X) \rightarrow 0$ when $k \rightarrow +\infty$.

What is coupling, for β -mixing sequences?

It is a method for building a twin sequence $u_i^* = (X_i^*, \varepsilon_i^*)$ independent by blocks of size $q = q(n)$ with a price of substitution of order the mixing coefficient β_q . Talagrand applied to the u_i^* .

Specificity of regression: the variance term in the Talagrand \mathbb{H}^2 is computed without the mixing inequalities, so with the same penalty as in the independent case.

Martingale strategy

Useful remark:

$$\sum_{i=1}^n \varepsilon_i h(X_i) \text{ is a } \mathcal{F}_n\text{-martingale}$$

with $\mathcal{F}_n = \sigma(X_i, i \leq n+1, \varepsilon_i, i \leq n)$.

Sub-gaussian noise assumption: $\mathbb{E}(e^{u\varepsilon_1}) \leq \exp\left(\frac{u^2 s^2}{2}\right), \forall u \in \mathbb{R}$.

$$\mathbb{P}\left(\sum_{i=1}^n \varepsilon_i h(X_i) \geq na, \quad \|h\|_n^2 \leq v^2\right) \leq \exp\left(-\frac{na^2}{2s^2v^2}\right).$$

The deviation of the supremum is deduced by a $\mathbb{L}_2 - \mathbb{L}_\infty$ -chaining method, which became universal.

Interest: handle large (irregular) collections of models. No mixing coefficients here (but still for Tropp).

Diffusion models

Recall that diffusion model are defined by

$$d\mathbf{X}_t = \mathbf{b}(\mathbf{X}_t)dt + \sigma(\mathbf{X}_t)dW_t \text{ with } X_0 \sim \mu$$

and W_t a standard Brownian motion. **Observations** $(X_{i\Delta})_{1 \leq i \leq n}$.
 Δ small and $n\Delta$ large (high frequency data)

We define

$$Y_{i,\Delta} = \frac{X_{(i+1)\Delta} - X_{i\Delta}}{\Delta}.$$

Approximation 1

$$Y_{i,\Delta} = b(X_{i\Delta}) + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} \sigma(X_s) dW_s}_{:= Z_{i,\Delta}} + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} (b(X_s) - b(X_{i\Delta})) ds}_{R_{i,\Delta}^{(1)}}.$$

The "noise" $Z_{i,\Delta}$ depends on X_s so coupling is uneasy and loses the independence structure \Rightarrow Martingale method.

Martingale method for diffusions

Gaussian assumption on the noise free! (Brownian motion).

$$\nu_n(h) = \sum_{i=1}^n h(X_{i\Delta}) \int_{i\Delta}^{(i+1)\Delta} \sigma(X_s) dW_s = \int_0^{n\Delta} \tilde{h}(X_s) \sigma(X_s) dW_s$$

with $\tilde{h}(X_s) = h(X_{i\Delta})$ for $i\Delta \leq s < (i+1)\Delta$.

$$\mathbb{P} \left(\sum_{i=1}^n h(X_{i\Delta}) Z_{i\Delta} \geq na, \quad \|h\|_n^2 \leq v^2 \right) \leq \exp \left(-\frac{n\Delta a^2}{2\|\sigma\|_\infty^2 v^2} \right).$$

Under σ bounded due to $\langle M \rangle_{(n+1)\Delta} = \sum_{i=1}^n t^2(X_{i\Delta}) \int_{i\Delta}^{(i+1)\Delta} \sigma^2(X_s) ds$.

Residual terms to bound.

Least squares penalized estimator

$$\hat{m} = \arg \min_{m \in \hat{\mathcal{M}}_n} \left[\gamma_n(\hat{b}_m) + \text{pen}(m) \right]$$

under conditions and on compact support is such that

$$\mathbb{E}(\|\hat{b}_{\hat{m}} - b_A\|_n^2) \leq C \inf_{m \in \hat{\mathcal{M}}_n} \left(\|b_m - b_A\|_f^2 + \frac{\sigma_1^2 D_m}{n\Delta} \right) + K' \Delta + \frac{K''}{n\Delta}$$

for

$$\text{pen}(m) \geq \kappa \sigma_1^2 \frac{D_m}{n\Delta},$$

where σ_1 is an upper bound on σ .

\Rightarrow Asymptotic is with respect to $n\Delta$.

Coupling method for diffusions

Works with the approximation

$$\begin{aligned}
 Y_{i,\Delta} = & b(X_{i\Delta}) + \underbrace{\sigma(X_{i\Delta}) \frac{W_{(i+1)\Delta} - W_{i\Delta}}{\Delta}}_{x,w \text{ separated}} + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} [b(X_s) - b(X_{i\Delta})] ds}_{R_{i,\Delta}^{(1)}} \\
 & + \underbrace{\frac{1}{\Delta} \int_{i\Delta}^{(i+1)\Delta} [\sigma(X_s) - \sigma(X_{i\Delta})] dW_s}_{:=R_{i,\Delta}^{(2)}}.
 \end{aligned}$$

Price: one more residual term to control.

Tropp-Chernov generalization to dependent variables is possible

Non compact support results.

Diffusions in FDA: back to independence

$$\gamma_n(h) = \frac{1}{nT} \sum_{i=1}^n \left(\int_0^T h^2(X_i(u)) du - 2 \int_0^T h(X_i(u)) dX_i(u) \right)$$

$$\hat{Z}_m = \left(\frac{1}{nT} \sum_{i=1}^n \int_0^T \varphi_j(X_i(u)) dX_i(u) \right)_{j=0, \dots, m-1}$$

and the $m \times m$ -matrix

$$\hat{\Psi}_m = \left(\frac{1}{nT} \sum_{i=1}^n \int_0^T \varphi_j(X_i(u)) \varphi_\ell(X_i(u)) du \right)_{j, \ell=0, \dots, m-1}.$$

Then, provided that $\hat{\Psi}_m$ is a.s. invertible,

$$\hat{\mathbf{a}}_m = \hat{\Psi}_m^{-1} \hat{Z}_m.$$

$\hat{\Psi}_m$ is no longer of the form $(1/n) \hat{\Phi}_m^\top \hat{\Phi}_m$.

$$\|h\|_n^2 = \frac{1}{nT} \sum_{i=1}^n \int_0^T h^2(X_i(u)) du, \quad \langle s, t \rangle_n = \frac{1}{nT} \sum_{i=1}^n \int_0^T t(X_i(u)) s(X_i(u)) du,$$

$$\nu_n(h) = \frac{1}{nT} \sum_{i=1}^n \int_0^T h(X_i(u)) \sigma(X_i(u)) dW_i(u).$$

Therefore,

$$\mathbb{E}\|h\|_n^2 = \|h\|_{f_T}^2, \quad \mathbb{E}\langle h, h^* \rangle_n = \langle h, h^* \rangle_{f_T}$$

and

$$\mathbb{E}\nu_n(h) = 0, \quad \mathbb{E}\nu_n^2(h) = \|h\sigma\|_{f_T}^2/nT$$

where f_T is an integral of the transition density.

Martingale + chaining strategy for deviation. T fixed.

Talagrand/Truncation strategy possible?

Discretization, Denis, Dion, Martinez (2021)

Concluding remarks.

- Improvement over time for generalizations and improvement of results and conditions!
- Question. Tropp-Chernov for unbounded variables.
- Question. Ready-to-use deviation of the empirical process under moment conditions in the non bounded case.
- Dimension ≥ 1 for X : Dussap's paper in the multivariate case and the algebra of hypermatrices.
- Higher dimension: Additive model + Lasso + Model selection. In which order?

Thank you for your attention !

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